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International Journal of Economics and Financial Issues ISSN: 2146-4138 available at <http://www.econjournals.com> International Journal of Economics and Financial Issues, 2018, 8(5), 96-102. International Journal of Economics and Financial Issues | Vol 8 • Issue 5 • 2018 96 Bayesian Approach for Indonesia Inflation Forecasting Zul Amry* Department of Mathematics, State University of Medan, Indonesia. *Email: zul.amry@gmail.com ABSTRACT This paper presents a Bayesian approach to find the Bayesian model for the point forecast of ARMA model under normal-gamma prior assumption with quadratic loss function in the form of mathematical expression.

The conditional posterior predictive density is obtained from the combination of the posterior under normal-gamma prior with the conditional predictive density. The marginal conditional posterior predictive density is obtained by integrating the conditional posterior predictive density, whereas the point forecast is derived from the marginal conditional posterior predictive density. Furthermore, the forecasting model is applied to inflation data and compare to traditional method.

The results show that the Bayesian forecasting is better than the traditional forecasting.

Keywords: ARMA Model, Bayes Theorem, Inflation, Normal-gamma Prior JEL

Classifications: C13, C15, C22 1. INTRODUCTION Bayes theorem calculates the posterior distribution as proportion to the product of a prior distribution and the likelihood function.

The prior distribution is a probability model describing the knowledge about the parameters before observing the currently by the available data. Main idea of Bayesian forecasting is the predictive distribution of the future given the fast data follows directly from the joint probabilistic model. The predictive distribution is derived from the

sampling predictive density, weighted by the posterior distribution (Bijak, 2010).

This is to and (2015) the problem Bayesian for ARMA under prior. papers to research Amry Fan and Yao (2008), Kleibergen and Hoek (1996), and Uturbey (2006) also discussed the Bayesian analysis for ARMA model. This paper focuses to find the mathematical expression of the Bayes estimator prior with loss and compare traditional method. 2.

MATERIALS AND METHODS The materials in this paper are some theories in mathematics and integration, and the univariate student's t-distribution and inflation data. The method is study of literatures by applying the Bayesian analysis under normal-gamma prior assumption. ARMA (p, q) model (Liu, 1995) is defined by: $y_t = \sum_{i=1}^p \phi_i y_{t-i} + \sum_{j=1}^q \theta_j \epsilon_{t-j} + \epsilon_t$ (1) Where $\{\epsilon_t\}$ is i.i.d normal random variables with $\epsilon_t \sim N(0, \sigma^2)$, $\sigma^2 > 0$ and unknown, ϕ_i and θ_j are parameters.

The Bayes theorem (Ramachandran and Tsokos, 2009) stated as: $p(y|x) = \frac{p(x|y) p(y)}{p(x)}$ (2) Where $p(y|x)$ is posterior distribution, $p(x|y)$ is likelihood function and $p(y)$ is prior distribution. A quantity, is to a distribution n degrees of freedom with mode μ and scale parameter $t > 0$ if it has the probability density function (Pole et al.,

1994): $p(x) = \frac{1}{\Gamma(n/2) 2^{n/2} \Gamma(n/2)} \left(\frac{x-\mu}{t}\right)^{-(n/2)-1} \exp\left\{-\frac{1}{2t} \left(\frac{x-\mu}{t}\right)^2\right\}$ (3) International Journal of Economics and Financial Issues | Vol 8 • Issue 5 • 2018 97 The mean is $E(X) = \mu$ and the variance is $Var(X) = \frac{2t}{n-2}$, if $n > 2$ In the Bayesian approach the point forecast determined based the estimator.

to & (2006), is an of, a loss is real-valued function: $L(\hat{y}_t, y_t) = \frac{1}{2} (\hat{y}_t - y_t)^2$ (4) For quadratic function, Bayes is mean of the posterior distribution (DeGroot, 2004). 3. RESULTS The k-step-ahead point forecast of y_{n+k} , is defined by: $\hat{y}_{n+k} = E(y_{n+k} | \mathcal{F}_n)$ (5) Where $\mathcal{F}_n = \sigma(y_1, \dots, y_n)$ Based on the equation (1) can be obtained residuals: $\epsilon_t = y_t - \sum_{i=1}^p \phi_i y_{t-i} - \sum_{j=1}^q \theta_j \epsilon_{t-j}$ (6) By conditioning the first p observations and letting $\epsilon_p = \epsilon_{p-1} = \dots = \epsilon_r = 0$, where $r = \min(0, p+1-q)$, one may approximate by Box & Jenkins, the likelihood function for parameters $\theta = (\theta_1, \theta_2, \dots, \theta_p, \theta_1, \theta_2, \dots, \theta_q)$ and t based is: $L(y) = \prod_{t=r+1}^n \frac{1}{\sigma^2} \exp\left\{-\frac{1}{2\sigma^2} \left(\frac{y_t - \sum_{i=1}^p \phi_i y_{t-i} - \sum_{j=1}^q \theta_j \epsilon_{t-j}}{\sigma}\right)^2\right\}$ (7) The equation (7) can be expressed as: $L(y) = \prod_{t=r+1}^n \frac{1}{\sigma^2} \exp\left\{-\frac{1}{2\sigma^2} (y_t - \sum_{i=1}^p \phi_i y_{t-i} - \sum_{j=1}^q \theta_j \epsilon_{t-j})^2\right\}$ (8) Where $B_t = (y_t, y_{t-1}, \dots, y_{t+1-p}, \epsilon_t, \epsilon_{t-1}, \dots, \epsilon_{t+1-q})$ By letting $U = (y_1, y_2, \dots, y_n, \epsilon_1, \epsilon_2, \dots, \epsilon_n)$ $p \times p$ matrix $\Sigma = \text{Cov}(U)$ $p \times p$ matrix $\Lambda = \text{Cov}(y)$ $p \times p$ matrix $\Gamma = \text{Cov}(\epsilon)$ $p \times p$ matrix $\Phi = \text{Cov}(y, \epsilon)$ $p \times p$ matrix $\Psi = \text{Cov}(\epsilon, y)$ $p \times p$ matrix $\Theta = \text{Cov}(y, \epsilon, y)$ $p \times p$ matrix $\Xi = \text{Cov}(\epsilon, y, \epsilon)$ $p \times p$ matrix $\Upsilon = \text{Cov}(y, \epsilon, y, \epsilon)$ $p \times p$ matrix $\Omega = \text{Cov}(\epsilon, y, \epsilon, y)$ $p \times p$ matrix $\Sigma^{-1} = \text{Cov}^{-1}(U)$ $p \times p$ matrix $\Lambda^{-1} = \text{Cov}^{-1}(y)$ $p \times p$ matrix $\Gamma^{-1} = \text{Cov}^{-1}(\epsilon)$ $p \times p$ matrix $\Phi^{-1} = \text{Cov}^{-1}(y, \epsilon)$ $p \times p$ matrix $\Psi^{-1} = \text{Cov}^{-1}(\epsilon, y)$ $p \times p$ matrix $\Theta^{-1} = \text{Cov}^{-1}(y, \epsilon, y)$ $p \times p$ matrix $\Xi^{-1} = \text{Cov}^{-1}(\epsilon, y, \epsilon)$ $p \times p$ matrix $\Upsilon^{-1} = \text{Cov}^{-1}(y, \epsilon, y, \epsilon)$ $p \times p$ matrix $\Omega^{-1} = \text{Cov}^{-1}(\epsilon, y, \epsilon, y)$ $p \times p$ matrix $X = (y_1, y_2, \dots, y_n, \epsilon_1, \epsilon_2, \dots, \epsilon_n)$

0 1 2 1 _ Where ey ye tp pn tt it ij tj j q i p = - - = + + - - = = ? ? _ _ _ ... _ ff ? , , , 12 1 1 et, et -1 , , , et - q can be obtained via: ey B tt T t = - - ? ? 1 (9) Where _ _ _ ... _ _ _ ? ? ? ? = (, , ,) ff f 12 12 pq From the likelihood function in equation (8) can be obtained: yB yB yB yB yy y tt pp pp nk nk tp nk pp p - + + + - = + + - + - = + + = ? 11 21 2 1 1 11 ? (, , , , ,) (, , , , ,) ? ? ? ye ee yy yy ee e pp pq pp pp pp 11 1 21 21 2 - + - + + - + qq nk nk nk nk pn kn kq T yy yy ee UX) (, , , ,) + + = + + - + - - + - - ? ? ? 21 21 0 ? ? ? T t tp nk T p T p T nk BB BB - = + + - + - -) = () + () + + () ? 1 2 1 1 2 1 2 2 2 12 ? ? ? , , ? ? ? ? ? ? ? pq T pp pp pq yy ye ee , , , , , , , 12 11 11 2 () ? ? ? ? ? ? ? ? - - + - + () + + + + - ? ? ? ? ? 12 12 21 22 12 , , , , , , , , ? ? ? pq T pp pp pq yy ye ee () ? ? ? ? ? ? ? ? + + () - + - - 2 12 12 23 ? ? ? ? ? ? ? ? , , , , , , , pq T nk nk nk yy y - - + - + - - () ? ? ? ? ? ? ? ? = 12 31 2 pn kn kn kq TT ee e UU , , , () ? ? ? **International Journal of Economics and Financial Issues** | Vol 8 • Issue 5 • 2018 98 Such that the likelihood function in equation (8) can be expressed as: LS e yU XU U n nk p t TT TT tp nk ? ? ? ? , | ex p () () * () ? ? ? () ? - - + + - - = + + 1 2 2 0 1 2 2 - - ? ? ? ? ? ? ? ? ? ? ? ? ? ? ? ? 1 ? - - + ? ? ? ? ? ? ? ? ? ? ? ? ? ? ? ? ? ? + - - = + - ? ey VW nk p t TT tp nk () ex p 1 2 2 1 1 2 2 ? ? ? ? ? ? ? (10) Where UT X 0 = V and UUT = W 3.1.

Posterior Distribution According to Broemeling and Shaarawy's suggestion (1988), the normal-gamma prior of parameters μ and t is: $p(\mu, t) \propto \exp(-\frac{1}{2t}(\mu - \beta)^T a^{-1}(\mu - \beta) - \frac{1}{2t} \text{tr}(b^{-1}t))$ (11) Where $1 \sim N(-1, 1)$, $1 \sim \text{GAM}$ Q a definite matrix of the order $(p + q)$, a and β are parameters.

By applying the Bayes theorem to equation (10) and (11), the posterior distribution of μ and t is: $p(\mu, t) \propto \exp(-\frac{1}{2t}(\mu - \beta)^T a^{-1}(\mu - \beta) - \frac{1}{2t} \text{tr}(b^{-1}t) - \frac{1}{2t}(\mu - \beta)^T A^{-1}(\mu - \beta) - \frac{1}{2t} \text{tr}(B^{-1}t))$ (12) Where $WQ P$ and $yQ K$ T tp nk += += = += + - ? 2 1 1 2 $\mu \beta$ 3.2.

Conditional Posterior Predictive Density Based on ey ye tt it ij tj j q i p = - - - - = = ? ? ? ? 1

1 with $e_t \sim N(0, \sigma^2)$ (be obtained from the joint density of (y_1, \dots, y_{n+k})) $\exp\{-\frac{1}{2\sigma^2} \sum_{t=1}^{n+k} (y_t - \mu)^2\}$ (13) predictive density of Y_{n+k} : $f_{Y_{n+k}}(y_{n+k} | y_1, \dots, y_n) = \int f_{Y_{n+k}}(y_{n+k} | \mu) f_{\mu}(\mu | y_1, \dots, y_n) d\mu$ International Journal of Economics and Financial Issues | Vol 8 • Issue 5 • 2018 99-108
Based on the equation (12) and (14) can be obtained the conditional posterior predictive density of Y_{n+k} : $f_{Y_{n+k}}(y_{n+k} | y_1, \dots, y_n) = \int f_{Y_{n+k}}(y_{n+k} | \mu) f_{\mu}(\mu | y_1, \dots, y_n) d\mu$ (15) Where $G = P + R$ 3.3.

Marginal Conditional Posterior Predictive The marginal conditional posterior predictive density of Y_{n+k} can be obtained by integrating the conditional posterior predictive density in equation (15): density in equation (15): $f_{Y_{n+k}}(y_{n+k} | y_1, \dots, y_n) = \int f_{Y_{n+k}}(y_{n+k} | \mu) f_{\mu}(\mu | y_1, \dots, y_n) d\mu$ (16) (17) (18) (19) (20) (21) (22) (23) (24) (25) (26) (27) (28) (29) (30) (31) (32) (33) (34) (35) (36) (37) (38) (39) (40) (41) (42) (43) (44) (45) (46) (47) (48) (49) (50) (51) (52) (53) (54) (55) (56) (57) (58) (59) (60) (61) (62) (63) (64) (65) (66) (67) (68) (69) (70) (71) (72) (73) (74) (75) (76) (77) (78) (79) (80) (81) (82) (83) (84) (85) (86) (87) (88) (89) (90) (91) (92) (93) (94) (95) (96) (97) (98) (99) (100)

Data, Stationarity, Identification, and Model Selection Data 204 y, monthly in from January 2000 to December 2016 is displayed in Figure 1. Plot of ACF in Figure 2 in the form of damped sine wave, indicates that the time series data is stationary. Plot ACF in Figure 2 is disconnected after lag plot PACF Figure 3 is disconnected after second lag, these indicate that the appropriate model for data ARMA(2,1).

The the of and value is presented as Table 1. The smallest AIC value in Table 1 is 331.79 on ARMA(1,1) model, it means the suitable model for the data is ARMA(1,1) model. In Yt, its model is written: $Y_t = 8530606 - 0.3335 Y_{t-1} + e_t$ (18) 4.2. Comparison to Traditional Method The comparison of point forecast between Bayesian forecasting in equation (17) with traditional forecasting in equation (18) is presented in the Table 2. Columns 2 through 4 containing the factual data, result of Bayesian forecasting, and result of traditional forecasting.

The comparison of forecast accuracy between Bayesian method and traditional method is presented in the Table 3. Rows 2 through 5 containing the RMSE, MAE, MAPE and U-Statistics. The results show that the forecast accuracy value of the Bayesian method is smaller than the traditional method, so in this case it is concluded that the forecast accuracy for the Bayesian forecasting is better than the traditional forecasting.

The comparison of descriptive statistics between the Bayesian method and the traditional method is presented in the Table 4. Columns 2 through mean, third quartile (Q3), maximum (Max), and standard deviation for factual 192 data the of forecasting for the 12 steps ahead, and 192 factual data and the result of traditional forecasting for the 12 steps ahead.

Plot of factual data, Bayesian and traditional forecasting for the 12 steps ahead is displayed in Figure 4, shows that the plot of factual data is more varied to the plot of Bayesian than the traditional forecasting. 5. CONCLUSION of the point forecast for Bayesian forecasting under normal- gamma prior. The conditional posterior predictive density Table 3: Comparison of forecast accuracy Forecast accuracy Bayesian Traditional RMSE 0.12476883 0.2545024 MAE 0.09569079 0.1962556 MAPE 47.6807038 81.4006722 U-statistics 0.16897685 0.4092601 Table 4: Comparison of descriptive statistics Data Min.

Q1 Median Mean Q3 Max SD Factual 1–204 140 1.14 0.5 0.55 0.9 3.3 0.589 Factual 1–192, Bayesian 193–204 140 1.13 0.5 0.55 0.9 3.3 0.590 Factual 1–192 Trad. 193–204 140 1.12 0.4 0.54 0.9 3.3 0.588 International Journal of Economics and Financial Issues | Vol 8 • Issue 5 • 2018 102 is obtained by multiplying the normal-gamma prior with the conditional predictive density.

The marginal conditional posterior predictive density is obtained by integrating the conditional posterior predictive density to parameters, whereas the point forecast is derived based on the mean of marginal conditional posterior predictive density that has the univariate. The computational results show that the forecast accuracy value of Bayesian forecasting is smaller than the traditional forecasting, while the values of descriptive statistics show that the Bayesian forecasting is closer to the factual data than the traditional forecasting, it indicates that the Bayesian forecasting is better than the traditional forecasting. REFERENCES Amry, Z.

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